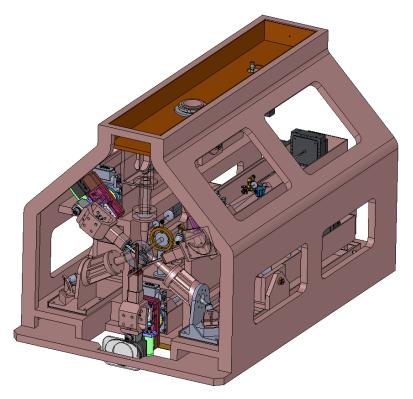


NGAO Laser Guide Star



12/07/2009 MINI-REVIEW (MINI-ANSWERS)

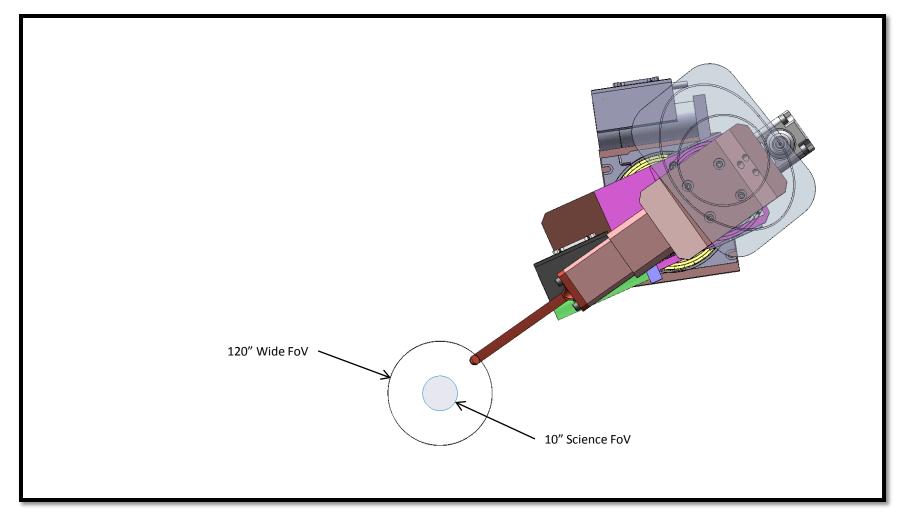




Laser Guide Star Mini-Review mini-answers

1)	Movie with the pick-off arms moving	.P 3
2)	Folded motor has additional gear train - check specs for backlash	P4
3)	Illustrations shouldn't show obscuration of the science field.	OK, No Action!
4)	Use shallower angles at the tip-tilt and fold mirror (for making the overall length shorter	P5
5)	Can we use a yaw-pitch mechanism	Stalcup
6)	Do we need a pick-off for this ast all or use a tetrahedron	P6 & 7
7)	Distortion of the on-sky of the fixed asterism on sky	Stalcup
8)	Eye-bolts to lift the LGS WFS assembly to facilitate lifting	.On-Going
9)	Access to the linear stage is limited (the structure is 200 Kgs). Jack screws	On-Going
10) Tracking of the sodium error needs more thought (PW)	
11)	Addition of a custom "Fail-Safe" Device	P8 & 9





2) Backlash elimination

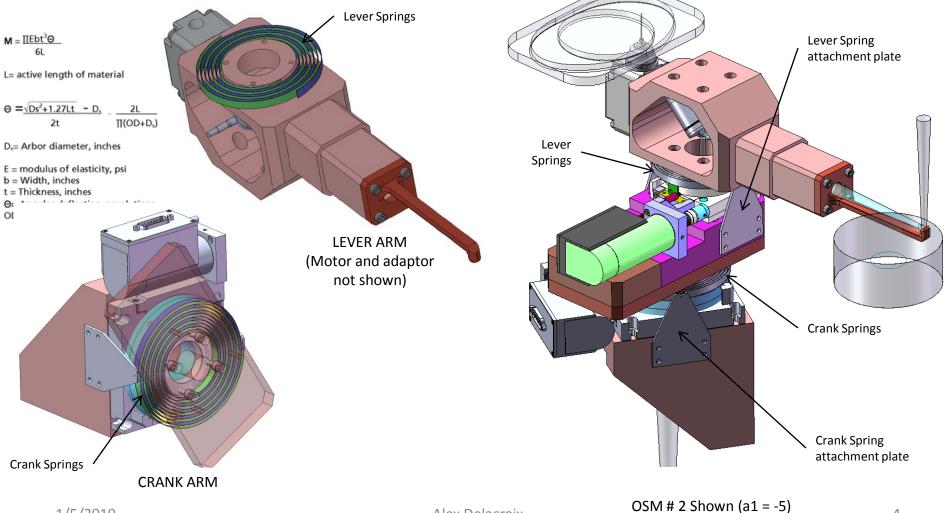


The backlash specified by the vendor is 200 μ rad (0.011°) for each stages.

This would translate by a field inaccuracy of $(300 \tan 0.011) + (260 \tan 0.011) = 0.112 \text{ mm}$

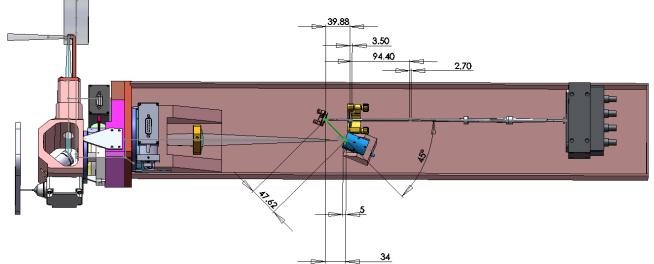
Adding a constant 0.5 Lbs-in (.06Nm) torque (preloaded Spiral Spring) eliminates the backlash for any position of the Crank – Arm over a 360° rotation.

Adding 2 springs diametrically opposed prevents the addition of an undesired torque across the axis of rotation.

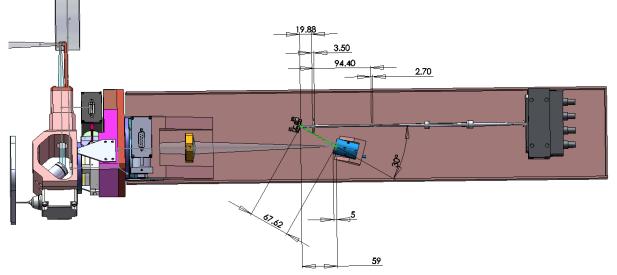


3) Closing the Fold Mirror angle





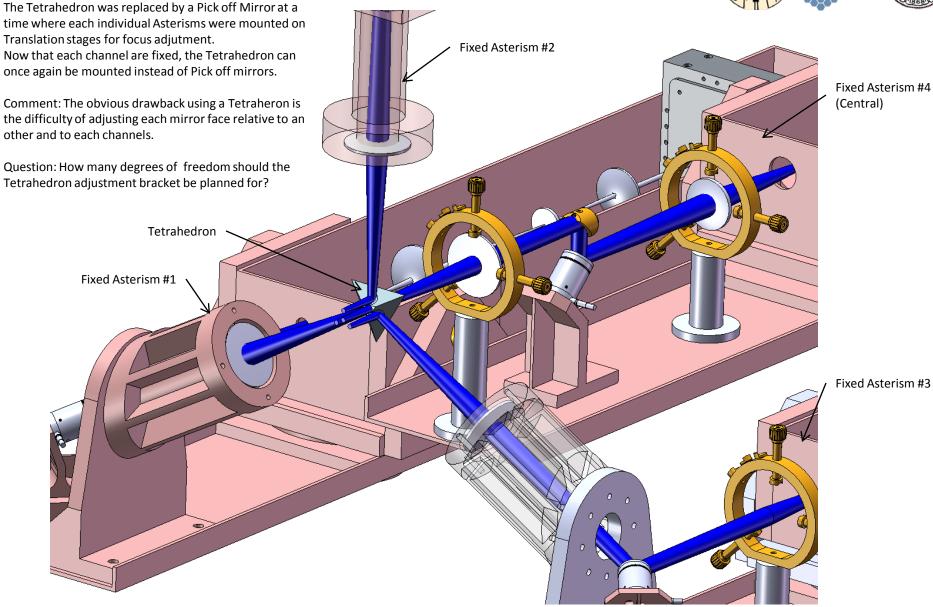
Using a 45° angle instead of a 90° angle allows to shorten the beam 34mm.

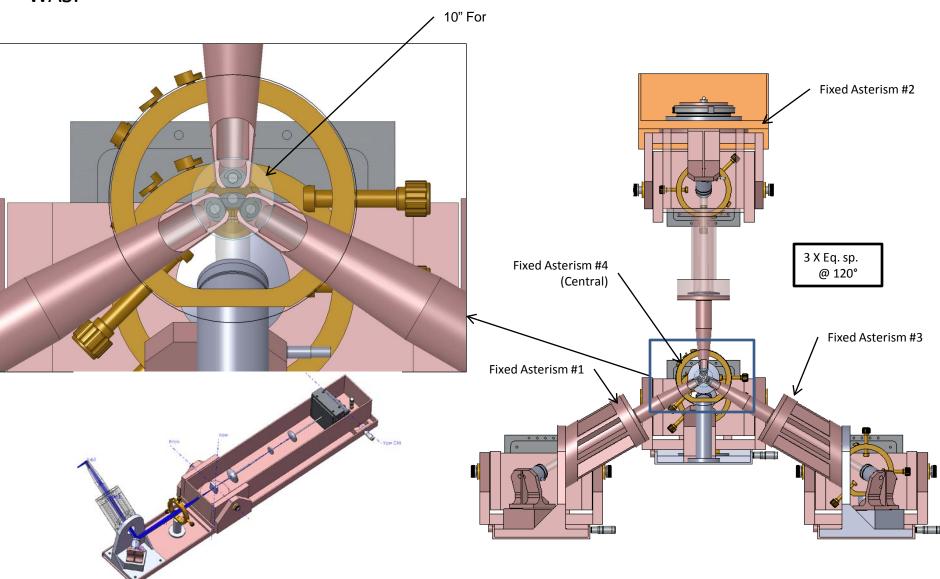


Using a 30° angle instead of a 90° angle allows to shorten the beam 59mm.

4) Replacing the Fixed Asterism Pick off with a Tetrahedron





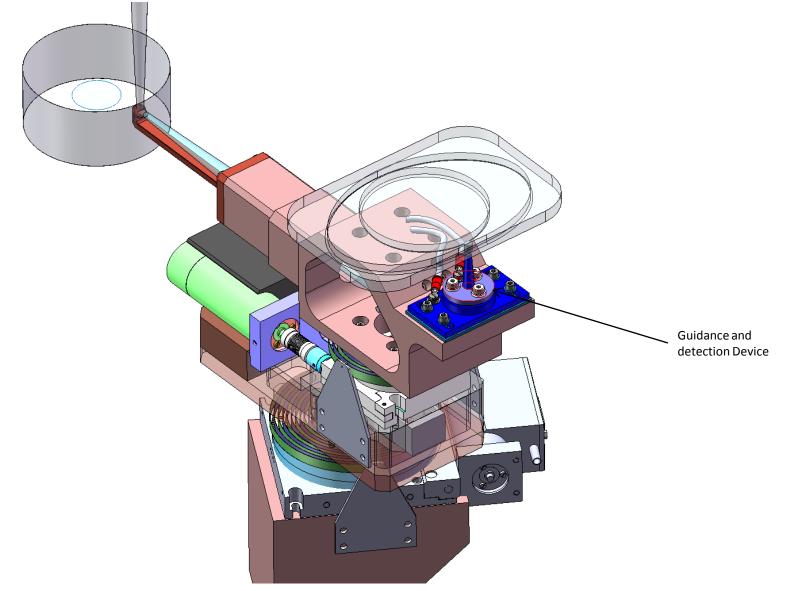


4.1) Replacing the Fixed Asterism Pick off with a Tetrahedron WAS:

5) Guidance and detection device



A single custom Device is guiding the arm through its allowed path after detecting software error.



Alex Delacroix

5.1) Guidance and detection device detail

The device is composed of an electrically insulated Wobbler and a base bracket.

The wobbler is composed of a Ball Bearing Track Roller (Mc Master 3668K2), a steel shaft threaded through the Normally Open Switch, held on the base between 3 compression spring and 3 shoulder bolts.

The wobbler is wired to the control board.

Custom Track 🗕

Operation:

Shortly after the arm deviates from its allowed path, the track roller will contact the custom track and the spring mounted wobbler will deflect 1 mm before closing the circular Normally Open Switch to signal the anomaly and shut down the crank and lever stages.

Full retraction can be safely conducted by rotating the Crank stage only until the Initial Position micro-switch signal the return to Origin position is achieved.

WOBBLER ASSEMBLY

The Lever will be safely guided into approximate reset the track roller into the Track.

position by the action of

